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### **Proposition**

*Images of linear functions of convex sets are convex.*

#### Proof.

*Let C be a convex set and f* : *C* → R *<sup>N</sup> be a linear function. Define*  $D = \{y \in \mathbb{R}^N \mid y = f(x), x \in C\}$  *Let*  $y_1, y_2 \in D$  and let  $0 \le \lambda \le 1$ . *Then there exists*  $x_1, x_2 \in C$  *such that*  $y_1 = f(x_1)$  *and*  $y_2 = f(x_2)$ *.* 

$$
\lambda y_1 + (1 - \lambda y_2) = \lambda f(x_1) + (1 - \lambda) f(x_2)
$$
  
= 
$$
f(\lambda x_1 + (1 - \lambda) x_2)
$$

*But x*<sub>1</sub>,  $x_2 \in C$  and *C* is convex. Therefore  $\lambda x_1 + (1 - \lambda)x_2 \in C$ . *Hence, f*( $\lambda x_1 + (1 - \lambda)x_2$ )  $\in$  *D. And this makes*  $\lambda y_1 + (1 - \lambda y_2) \in D$ 

## <span id="page-2-0"></span>Dependence on Prior Class Probabilities

### **Proposition**

*Expected economic gain for a decision rule is an affine function of the expected economic conditional gains with coefficients P*(*c*<sup>1</sup>), ..., *P*(*c*<sup>*K*-1</sup>).

#### Proof.

$$
E[e; f] = \sum_{j=1}^{K} E[e | c^{j}; f] P(c^{j})
$$
  
\n
$$
= \sum_{j=1}^{K-1} E[e | c^{j}; f] P(c^{j}) + E[e | c^{K}; f] (1 - \sum_{j=1}^{K-1} P(c^{j}))
$$
  
\n
$$
= \sum_{j=1}^{K-1} \{ E[e | c^{j}; f] - E[e | c^{K}; f] \} P(c^{j}) + E[e | c^{K}; f]
$$

 $\leftarrow$ 

 $\mathbb{R}^n \times \mathbb{R}^n \xrightarrow{\mathbb{R}^n} \mathbb{R}^n \times \mathbb{R}^n \xrightarrow{\mathbb{R}^n} \mathbb{R}^n$ 

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$$
E[e \mid c^j; f] = \sum_{d \in D} \sum_{k=1}^K e(c^j, c^k) P(d \mid c^j) f_d(c^k)
$$



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## <span id="page-4-0"></span>Expected Conditional Gain and Expected Gain

$$
E[e | o^j; f] = \sum_{d \in D} \sum_{k=1}^K e(o^j, c^k) P(d | o^j) f_d(c^k)
$$
  
\n
$$
E[e; f] = \sum_{j=1}^K E[e | o^j; f] P(o^j)
$$
  
\n
$$
= \left[ \sum_{j=1}^{K-1} E[e | o^j; f] P(o^j) \right] + \left[ E[e | c^K; f] (1 - \sum_{j=1}^{K-1} P(o^j)) \right]
$$
  
\n
$$
= \left[ \sum_{j=1}^{K-1} \{ E[e | o^j; f] - E[e | c^K; f] \} P(o^j) \right] + E[e | c^K; f]
$$

$$
E[e; f1] = [2 - (-1)]P(c1) + (-1) = 3.0P(c1) - 1
$$
  
\n
$$
E[e; f2] = [.5 - (-.7)]P(c1) + (-.7) = 1.2P(c1) - .7
$$
  
\n
$$
E[e; f3] = [1.1 - .2]P(c1) + .2 = 0.9P(c1) + .2
$$
  
\n
$$
E[e; f4] = [-.4 - .5]P(c1) + .5 = -0.9P(c1) + .5
$$
  
\n
$$
E[e; f5] = [1.4 - .5]P(c1) + .5 = 0.9P(c1) + .5
$$
  
\n
$$
E[e; f6] = [-.1 - .8]P(c1) - .8 = -0.9P(c1) + .8
$$
  
\n
$$
E[e; f7] = [.5 - 1.7]P(c1][1.7 = -1.2P(c1) + 1.7
$$
  
\n
$$
E[e; f8] = [-1.0 - 2.0]P(c1) + 2.0 = -3.0P(c1) + 2.0
$$

## <span id="page-5-0"></span>Expected Conditional Gain and Expected Gain



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### Dependence on Prior Class Probabilities

$$
E[e; f] = \sum_{j=1}^{K-1} \{E[e \mid c^j; f] - E[e \mid c^K; f]\} P(c^j) + E[e \mid c^K; f]
$$



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### Dependence on Class Prior Probabilities



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## Convex Functions

### **Definition**

A function  $h, h: \mathbb{R}^{\mathsf{N}} \to \mathbb{R},$  is a convex function if and only if for every  $\lambda$ ,  $0 \leq \lambda \leq 1$ ,

 $h(\lambda(x_1,...,x_N)+(1-\lambda)(y_1,...,y_N)) \leq \lambda h(x_1,...,x_N)+(1-\lambda)h(y_1,...,y_N)$ 



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# Bayes Gain is Convex



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### Bayes Gain Is Convex

$$
E[e; f] = \sum_{j=1}^{K} E[e | c^{j}; f] P(c^{j})]
$$
  

$$
G_B = \max_{f} E[e; f] \text{ Bayes Gain}
$$

Let  $f^n$ ,  $n = 1, \ldots N$  be the  $N = |C|^{|D|}$  deterministic decision rules.

Define for  $j = 1, \ldots, K$ 

$$
a_{jn} = E[e | c^j; f^n]
$$
  
\n
$$
p_j = P(c^j)
$$
  
\n
$$
G_B(P(c^1), \ldots, P(c^K)) = \max_{n} \sum_{j=1}^{K} E[e | c^j; f^n] P(c^j)
$$
  
\n
$$
G_B(p_1, \ldots, p_K) = \max_{n} \sum_{j=1}^{K} a_{jn} p_j
$$

### Bayes Gain Is Convex

#### Theorem

Let 
$$
p = (p_1, ..., p_K)
$$
 and  $q = (q_1, ..., q_K)$ . Let  $0 \le \lambda \le 1$ .  
\n
$$
G_B(\lambda p + (1 - \lambda)q) \le \lambda G_B(p) + (1 - \lambda)G_B(q)
$$

Proof.

$$
G_B(\lambda p + (1 - \lambda)q) = \max_{n} \sum_{j=1}^{K} a_{jn}(\lambda p_j + (1 - \lambda)q_j)
$$
  
\n
$$
= \max_{n} \left\{ \lambda \sum_{j=1}^{K} a_{jn}p_j + (1 - \lambda) \sum_{j=-1}^{K} a_{jn}q_j \right\}
$$
  
\n
$$
\leq \left[ \max_{n} \lambda \sum_{j=1}^{K} a_{jn}p_j \right] + \left[ \max_{n} (1 - \lambda) \sum_{j=1}^{K} a_{jn}q_j \right]
$$
  
\n
$$
\leq \lambda G_B(p) + (1 - \lambda) G_B(q)
$$

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### **Definition**

Let  $f: \mathbb{R}^N \to \mathbb{R}$ . The epigraph of  $f$ , denoted Epi(f) is the set of points lying on or above the graph of f.

$$
Epi(f) = \{(x, u) \in \mathbb{R}^N \times \mathbb{R} \mid u \ge f(x)\}
$$

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### **Proposition**

*If a function is convex then its epigraph is a convex set.*

#### Proof.

*Suppose f is convex.* Let  $(x, u)$ ,  $(y, v) \in$  *Epi*(*f*) and  $0 \le \lambda \le 1$ . *Then by definition of Epi(f),*  $f(x) < u$ *,*  $f(y) < v$  *and, therefore,*  $\lambda f(x) + (1 - \lambda)f(y) \leq \lambda u + (1 - \lambda)v$ . Since f is convex,  $f(\lambda x + (1 - \lambda)y) < \lambda f(x) + (1 - \lambda)f(y)$ *. But*  $\lambda f(x) + (1 - \lambda)f(y) \leq \lambda u + (1 - \lambda)v$ . Now by definition of *Epi*(*f*)*,* ( $\lambda x + (1 - \lambda)y$ ,  $\lambda u + (1 - \lambda)y$ ) ∈ *Epi*(*f*) *making Epi*(*f*) *convex.*

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### **Proposition**

*If the epigraph of a function is a convex set, then the function is convex.*

#### Proof.

*Suppose Epi*(*f*) *is a convex set. Then by definition of Epi*(*f*)*,*  $(x, f(x)) \in Epi(f)$  and  $(y, f(y)) \in Epi(f)$ . Since  $Epi(f)$  is convex,  $\lambda(x, f(x)) + (1 - \lambda)(y, f(y)) \in Epi(f)$ . Hence  $(\lambda x + (1 - \lambda y), \lambda f(x) + (1 - \lambda)f(y)) \in Epi(f)$ *. By definition of Epi*(*f*)*,*  $f(\lambda x + (1 - \lambda)y) < \lambda f(x) + (1 - \lambda)f(y)$ *. And by definition of a convex function, this implies that f is convex.*

 $(1, 4, 5)$   $(1, 4, 5)$   $(1, 4, 5)$ 

#### **Theorem**

*A function is convex if and only if its epigraph is a convex set.*



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## Basin sets of Convex Functions

### **Definition**

Let  $f:\mathbb{R}^N\rightarrow\mathbb{R}$  and  $c\in\mathbb{R}.$  A basin set of  $f$  is any set of the form

$$
L = \{x \in \mathbb{R}^N \mid f(x) \leq c\}
$$

#### Theorem

*Let C be a convex set, h be a convex function on C and*  $L = \{c \in C \mid h(c) \leq b\}$ . Then L is a convex set.

#### Proof.

*Let*  $x, y \in L$  *so that*  $h(x) \leq b$  *and*  $h(y) \leq b$  *and let*  $0 \leq \lambda \leq 1$ *. Since x*, *y* ∈ *L* ⊂ *C* and since *C* is a convex set,  $\lambda$ *x* + (1 −  $\lambda$ )*y* ∈ *C*. Then *since h is a convex function,*

$$
h(\lambda x + (1 - \lambda)y) \leq \lambda h(x) + (1 - \lambda)h(y) \leq \lambda b + (1 - \lambda)b = b
$$

*This implies by definition of L that*  $\lambda x + (1 - \lambda)y \in L$ .

## Minima Set of A Convex Function is Convex

### **Corollary**

*Let C* ⊂ R *<sup>N</sup> be a closed and bounded convex set. Let h* :  $C \rightarrow \mathbb{R}$  *be a convex function. Suppose b* = min<sub>c∈*C*</sub> *h*(*c*). *Then*  $M = \{x \in C \mid h(x) = b\}$  *is a convex set.* 

#### Proof.

*Note that since b* =  $\min_{c \in C} h(c)$ *, M* = { $x \in C | h(x) \le b$ }*. C being closed and bounded is needed because the minima of h may be on the boundary.*

#### Theorem

*Let C be a convex set and h be a convex function on C. Suppose h has a local minima at*  $x_0 \in C$ . Then for any  $x \in C$ ,  $h(x_0) \leq h(x)$ .

#### Proof.

*Let*  $x \in C$  *and*  $1 > \alpha > 0$  *be sufficiently small so that*  $(1 - \alpha)x_0 + \alpha x \in \mathbb{C}$ . Then,

$$
h(x_0) \leq h((1-\alpha)x_0 + \alpha x) \leq (1-\alpha)h(x_0) + \alpha h(x)
$$
  
\n
$$
0 \leq \alpha (h(x) - h(x_0))
$$
  
\n
$$
h(x_0) \leq h(x)
$$

### Dependence on Prior Class Probabilities

$$
E[e; f] = \sum_{j=1}^{K-1} \{E[e \mid c^j; f] - E[e \mid c^K; f]\} P(c^j) + E[e \mid c^K; f]
$$



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### Dependence on Class Prior Probabilities



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### Probabilistic Decision Rules

- Pick a prior probability *P*(*c* 1 )
- For decision rule *f* there is an Expected Gain *E*[*e*; *f*]
- For decision rule *g* there is a Expected Gain *E*[*e*; *g*]
- For decision rule  $\lambda f + (1 \lambda)g$ , the Expected Gain is

$$
\lambda E[e; f] + (1 - \lambda)E[e; g]
$$

• In between the Expected Gain for f and the Expected Gain for *g*

## Dependence on Class Prior Probabilities



### Expected gain of a mixed decision rule is the mixture of the expected gains of the component decision rules.

$$
E[e; \lambda f + (1 - \lambda)g, P(c^1)] = \lambda E[e; f, P(c^1)] + (1 - \lambda)E[e; g; P(c^1)]
$$

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# A Mixed Decision Rule is an affine function of *P*(*c* 1 )

#### Two Class Case

#### Proposition

*Let*  $0 \leq \lambda \leq 1$ *. Let*  $f_1$  *and*  $f_2$  *be two decision rules and Suppose there are two classes, then E*[e;  $\lambda f_1 + (1-\lambda)f_2$ ,  $P(c^1)$ ] *is an affine function of P*( $c^1$ )*.* 

#### Proof.

$$
E[e; f_1, P(c^1)] = \alpha_1 P(c^1) + \beta_1
$$
  
\n
$$
E[e; f_2, P(c^1)] = \alpha_2 P(c^1) + \beta_2
$$
  
\n
$$
E[e; \lambda f_1 + (1 - \lambda) f_2, P(c^1)] = \lambda(\alpha_1 P(c^1) + \beta_1) + (1 - \lambda)(\alpha_2 P(c^1) + \beta_2)
$$
  
\n
$$
= (\lambda \alpha_1 + (1 - \lambda)\alpha_2)P(c^1) + \lambda \beta_1 + (1 - \lambda)\beta_2
$$

### Probabilistic Decision Rules Are In Between

### Proposition

*Fix P*( $c^1$ ). Let  $0 \leq \lambda \leq 1$ .  $\mathcal{L}[H \in [\mathcal{C}^{\mathcal{C}}, \mathcal{C}^{\mathcal{C}}(C^{\mathcal{C}})] \leq \mathcal{C}^{\mathcal{C}}[\mathcal{C}^{\mathcal{C}}, \mathcal{C}^{\mathcal{C}}(C^{\mathcal{C}})] = \mathcal{C}^{\mathcal{C}}$ 

$$
E[e; f, P(c^1)] \leq E[e; \lambda f + (1-\lambda)g] \leq E[e; g, P(c^1)]
$$

#### Proof.

$$
E[e; f, P(c1)] = \lambda E[e; f, P(c1)] + (1 - \lambda)E[e; f, P(c1)]
$$
  
\n
$$
E[e; f, P(c1)] \leq \lambda E[e; f, P(c1)] + (1 - \lambda)E[e; g, P(c1)] \leq E[e; g, P(c1)]
$$
  
\n
$$
E[e; f, P(c1) \leq E[e; \lambda f + (1 - \lambda)g] \leq E[e; g, P(c1)]
$$

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## Dependence on Class Prior Probabilities



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### Dependence on Class Prior Probabilities



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### <span id="page-28-0"></span>Two Class Case Decision Rules of Mixture are Known

$$
E[e; f_5; P(c^1)] = .9P(c^1) + .5
$$
  
\n
$$
E[e; f_7; P(c^1)] = -1.2P(c^1) + 1.7
$$
  
\nSet E[e; f\_5; P(c^1)] = E[e; f\_7; P(c^1)]  
\n.9P(c^1) + .5 = -1.2P(c^1) + 1.7;  
\n2.1P(c^1) = 1.2  
\n
$$
P(c^1) = \frac{1.2}{2.1} = \frac{4}{7}
$$
  
\n
$$
P(c^2) = 1 - P(c^1) = \frac{3}{7}
$$

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### <span id="page-29-0"></span>Dependence of a Probabilistic Decision Rule on Priors

Suppose we know the deterministic decision rules to make up the mixture:  $f_5$  and  $f_7$ Since  $E[e; f] = E[e; c^1, f]P(c^1) + E[e; c^2, f]P(c^2)$ 

 $E[e; \lambda f^5 + (1 - \lambda)f^7] = E[e|c^1; \lambda f^5 + (1 - \lambda)f^7]P(c^1) + E[e|c^2; \lambda f^5 + (1 - \lambda)f^7]P(c^2)$ 

Since Expectation is a linear operator  $E[e|c; \alpha f + \beta g] = \alpha E[e|c; f] + \beta E[e|c; g]$ 

$$
E[e; \lambda f^5 + (1 - \lambda)f^7] = \left( \lambda E[e|c^1; f^5] + (1 - \lambda)E[e|c^1; f^7] \right) P(c^1) +
$$
  

$$
\left( \lambda E[e|c^2; f^5] + (1 - \lambda)E[e|c^2; f^7] \right) (1 - P(c^1))
$$
  

$$
= \left\{ \left( \lambda E[e|c^1; f^5] + (1 - \lambda)E[e|c^1; f^7] \right) - \right.
$$
  

$$
\left( \lambda E[e|c^2; f^5] + (1 - \lambda)E[e|c^2; f^7] \right) \right\} P(c^1) +
$$
  

$$
E[e|c^2; \lambda f^5 + (1 - \lambda)f^7]
$$

When there is no dependence on priors, the coefficient of  $P(c^1)$  must be zero

$$
\Bigl(\lambda E[e|c^1;f^5]+(1-\lambda)E[e|c^1;f^7]\Bigr)-\Bigl(\lambda E[e|c^2;f^5]+(1-\lambda)E[e|c^2;f^7]\Bigr) \quad = \quad 0
$$

The class conditional expected gains must be equal

$$
\lambda E[e|c^1; f^5] + (1 - \lambda)E[e|c^1; f^7] = \lambda E[e|c^2; f^5] + (1 - \lambda)E[e|c^2; f^7]
$$
  
\n
$$
E[e|c^1; \lambda f_5 + (1 - \lambda)f_7] = E[e|c^3; \lambda f_5 + (1 - \lambda)f_7]
$$

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## Dependence of a Probabilistic Decision Rule on Priors

$$
\lambda E[e|c^1; f^5] + (1-\lambda)E[e|c^1; f^7] - \left(\lambda E[e|c^2; f^5] + (1-\lambda)E[e|c^2; f^7]\right) = 0
$$

$$
\lambda\left(E[e|c^1; f^5] - E[e|c^1; f^7] - E[e|c^2; f^5] + E[e|c^2; f^7]\right) = E[e|c^2; f^7] - E[e|c^1; f^7]
$$

$$
\lambda = \frac{E[e|c^2; f^7] - E[e|c^1; f^7]}{E[c^1; f^5] - E[c^1; f^7] - E[e|c^2; f^5] + E[e|c^2; f^7]}
$$
  
= 
$$
\frac{1.7 - .5}{1.4 - .5 - .5 + 1.7} = \frac{1.2}{2.1} = \frac{4}{7}
$$

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# Require  $0 \leq \lambda \leq 1$

$$
\lambda = \frac{E[e|c^2; f^7] - E[e|c^1; f^7]}{E[c^1; f^5] - E[c^1; f^7] - E[e|c^2; f^5] + E[e|c^2; f^7]}
$$

 $\lambda \geq 0$  implies

$$
Sign\left(E[e|c^2; f^7] - E[e|c^1; f^7]\right) = Sign\left(E[c^1; f^5] - E[c^1; f^7] - E[e|c^2; f^5] + E[e|c^2; f^7]\right)
$$

 $\lambda$  < 1 implies

 $|E[e|c^2; f^7] - E[e|c^1; f^7]| \quad \leq \quad |E[c^1; f^5] - E[c^1; f^7] - E[e|c^2; f^5] + E[e|c^2; f^7]|$ 

If either of these inequality cannot be satisfied, it implies that the mixture of  $f<sub>5</sub>$  and  $f<sub>7</sub>$  is wrong

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### Expected Gain As A Function of Priors

The Expected economic gain can be related to the class conditional expected economic gain and prior probabilities.

$$
E[e; f] = \sum_{j=1}^{K} E[e | c^{j}; f] P(c^{j})
$$
  
\n
$$
= \left\{ \sum_{j=1}^{K-1} E[e | c^{j}; f] P(c^{j}) \right\} + E[e | c^{K}; f] P(c^{K})
$$
  
\n
$$
= \left\{ \sum_{j=1}^{K-1} E[e | c^{j}; f] P(c^{j}) \right\} + E[e | c^{K}; f] \left( 1 - \sum_{j=1}^{K-1} P(c_{j}) \right)
$$
  
\n
$$
= \left\{ \sum_{j=1}^{K-1} E[e | c^{j}; f] P(c^{j}) \right\} + E[e | c^{K}; f] - \sum_{j=1}^{K-1} E[e | c^{K}; f] P(c^{j})
$$

$$
E[e; f, P(c^1), \ldots, P(c^{K-1})] = \left\{ \sum_{j=1}^{K-1} \left( E[e | c^j; f] - E[e | c^K; f] \right) P(c^j) \right\} + E[e | c^K; f]
$$

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### Expected Gain As A Function Of Priors

$$
E[e; f, P(c^1), \ldots, P(c^{K-1})] = \left\{ \sum_{j=1}^{K-1} \left( E[e \mid c^j; f] - E[e \mid c^K; f] \right) P(c^j) \right\} + E[e \mid c^K; f]
$$

Two Class Case

$$
E[e; f, P(c1)] = (E[e | c1; f] – E[e | c2; f]) P(c1) + E[e | c2; f]
$$
  
=  $\alpha P(c1) + \gamma$   

$$
E[e; f1, P(c1)] = \alpha_{11} P(c1) + \gamma_1
$$
  

$$
E[e; f2, P(c1)] = \alpha_{21} P(c1) + \gamma_2
$$

When the expected gains of  $f_1$  and  $f_2$  are the same

$$
E[e; f_1, P(c^1)] = E[e; f_2, P(c^1)]
$$
  
\n
$$
\alpha_{11} P(c^1) + \gamma_1 = \alpha_{21} P(c^1) + \gamma_2
$$
  
\n
$$
(\alpha_{11} - \alpha_{21}) P(c^1) = \gamma_2 - \gamma_1
$$
  
\n
$$
P(c^1) = \frac{\alpha_{11} - \alpha_{21}}{\gamma_2 - \gamma_1}
$$

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$$
E[e; f_i; P(c^1), P(c^2)] = \alpha_{i1} P(c^1) + \alpha_{i2} P(c^2) + \gamma_i, i = 1, 2, 3
$$
  
\n
$$
E[e; f_i; P(c^1), P(c^2)] = E[e; f_3; P(c^1), P(c^2)], i = 1, 2
$$

$$
\alpha_{11} P(c^1) + \alpha_{12} P(c^2) + \gamma_1 = \alpha_{31} P(c^1) + \alpha_{32} P(c^2) + \gamma_3
$$
  
\n
$$
\alpha_{21} P(c^1) + \alpha_{22} P(c^2) + \gamma_2 = \alpha_{31} P(c^1) + \alpha_{32} P(c^2) + \gamma_3
$$

$$
\left(\begin{array}{cc}\alpha_{11}-\alpha_{31}&\alpha_{12}-\alpha_{32}\\ \alpha_{21}-\alpha_{31}&\alpha_{22}-\alpha_{32}\end{array}\right)\left(\begin{array}{c}P(c^1)\\P(c^2)\end{array}\right) = \left(\begin{array}{cc}\gamma_1-\gamma_3\\ \gamma_2-\gamma_3\end{array}\right)
$$

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### *K* Class Case

$$
E[e; f_k; P(c^1), \ldots, P(c^{K-1})] = \sum_{i=1}^{K-1} \alpha_{ki} P(c^i) + \gamma_k, k = 1, \ldots, K
$$
  

$$
E[e; f_k; P(c^1), \ldots, P(c^{K-1})] = E[e; f_K; P(c^1), \ldots, P(c^{K-1})], k = 1, \ldots, K-1
$$

$$
\begin{pmatrix}\n\alpha_{11} - \alpha_{K1} & \alpha_{12} - \alpha_{K2} & \dots & \alpha_{1,K-1} - \alpha_{K,K-1} \\
\vdots & \vdots & \ddots & \vdots \\
\alpha_{K-1,1} - \alpha_{K1} & \alpha_{K-1,2} - \alpha_{K2} & \dots & \alpha_{K-1,K-1} - \alpha_{K,K-1}\n\end{pmatrix}\n\begin{pmatrix}\nP(c^1) \\
\vdots \\
P(c^{K-1})\n\end{pmatrix} = \begin{pmatrix}\n\gamma_1 - \gamma_K \\
\vdots \\
\gamma_{K-1} - \gamma_K\n\end{pmatrix}
$$

$$
0 \le P(x^k) \le 1, k = 1,..., K - 1
$$
  

$$
\sum_{k=1}^{K} P(c^k) = 1
$$

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#### Two Class Case

$$
\lambda E[e|c^1; f^5] + (1 - \lambda)E[e|c^1; f^7] - (\lambda E[e|c^2; f^5] + (1 - \lambda)E[e|c^2; f^7]) = 0
$$
  

$$
E[e; \lambda f^5 + (1 - \lambda)f^7] = E[e|c^1; \lambda f^5 + (1 - \lambda)f^7]P(c^1) + E[e|c^2; \lambda f^5 + (1 - \lambda)f^7]P(c^2)
$$

Find  $P(c^1)$  that solves  $\alpha_{11}P(c^1) + \gamma_1 = \alpha_{21}P(c^1) + \gamma_2$ . Call the solution  $P_0(c^1)$ . Consider the expected gain of a mixed decision rule that has expected gain  $\alpha_{21}P_0(c^1)+\gamma_2$  for any prior  $P(c^1)$ .

$$
\lambda(\alpha_{11} P(c^1) + \gamma_1) + (1 - \lambda)(\alpha_{21} P(c^1) + \gamma_2) = \alpha_{21} P_0(c^1) + \gamma_2
$$

$$
(\lambda \alpha_{11} + (1 - \lambda)\alpha_{21})P(c^1) = \alpha_{21}P_0(c^1) + \gamma_2 - \lambda\gamma_1 - (1 - \lambda)\gamma_2
$$
  
=  $\alpha_{21}P_0(c^1) - \lambda(\gamma_1 + \gamma_2)$ 

Therefore,  $\lambda \alpha_{11} + (1 - \lambda)\alpha_{21} = 0$  and  $\lambda = \frac{-\alpha_{21}}{\alpha_{11} - \alpha_{21}} = \frac{\alpha_{21} P_0(c^1)}{\gamma_1 + \gamma_2}$ 

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### Finding The Convex Combination

Two Class Case Identity in  $P(c^1)$  meaning For all  $P(c^1)$ 

$$
0 \leq \lambda_1, \lambda_2 \leq 1
$$
  
\n
$$
\lambda_1 + \lambda_2 = 1
$$
  
\n
$$
\lambda_1(\alpha_{11}P(c^1) + \gamma_1) + \lambda_2(\alpha_{21}P(c^1) + \gamma_2) = \alpha_{21}P_0(c^1) + \gamma_2
$$

$$
(\lambda_1\alpha_{11}+\lambda_2\alpha_{21})P(c^1) = \alpha_{21}P_0(c^1)+\gamma_2-\lambda_1\gamma_1-\lambda_2\gamma_2
$$

This implies

$$
\lambda_1 \alpha_{11} + \lambda_2 \alpha_{21} = 0
$$
  
\n
$$
\lambda_1 \gamma_1 + \lambda_2 \gamma_2 = \alpha_{21} P_0(c^1) + \gamma_2
$$
  
\n
$$
\lambda_1 + \lambda_2 = 1
$$

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## Finding the Convex Combination

$$
\lambda_1 \alpha_{11} + \lambda_2 \alpha_{21} = 0
$$
  
\n
$$
\lambda_1 \gamma_1 + \lambda_2 \gamma_2 = \alpha_{21} P_0(c^1) + \gamma_2
$$
  
\n
$$
\lambda_1 + \lambda_2 = 1
$$

$$
\lambda_2 = -\lambda_1 \frac{\alpha_{11}}{\alpha_{21}}
$$
  

$$
\lambda_1 + \lambda_2 = \lambda_1 (1 - \frac{\alpha_{11}}{\alpha_{21}}) = 1
$$
  

$$
\lambda_1 = \frac{\alpha_{21}}{\alpha_{21} - \alpha_{11}}
$$

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### Finding the Convex Combination: Consistency Check

$$
0 \leq \lambda_1, \lambda_2 \leq 1
$$
  

$$
\lambda_1 = \frac{\alpha_{21}}{\alpha_{21} - \alpha_{11}}
$$

Either  $\alpha_{21} - \alpha_{11} > 0$  *or*  $\lt 0$ . If  $\alpha_{21} - \alpha_{11} > 0$  then

> $\alpha_{21} > \alpha_{11}$  $\alpha_{21} > 0$

If  $\alpha_{21} - \alpha_{11} < 0$  then,

 $\alpha_{21} \leq \alpha_{11}$  $\alpha_{21}$  < 0

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Once  $\lambda_1$  and  $\lambda_2$  are known, the exact value for  $P_0(c^1)$  can be determined.

$$
\lambda_1 \gamma_1 + (1 - \lambda_1) \gamma_2 = \alpha_{21} P_0(c^1) + \gamma_2 \n\lambda_1 (\gamma_1 - \gamma_2) = \alpha_{21} P_0(c^1) \n P_0(c^1) = \frac{\lambda_1 (\gamma_1 - \gamma_2)}{\alpha_{21}} \n= \frac{\alpha_{21}}{\alpha_{21} - \alpha_{11}} \frac{\gamma_1 - \gamma_2}{\alpha_{21}} \n= \frac{\gamma_1 - \gamma_2}{\alpha_{21} - \alpha_{11}}
$$

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### Finding The Convex Combination

*K* Class Case Identity in  $P(c^1) \ldots, P(c^{K-1})$ 

$$
\sum_{k=1}^{K} \lambda_k \left( \sum_{i=1}^{K-1} \alpha_{ik} P(c^i) + \gamma_k \right) = \sum_{i=1}^{K} \alpha_{Ki} P_0(c^i) + \gamma_K
$$
\n
$$
\sum_{i=1}^{K-1} \left( \sum_{k=1}^{K} \lambda_k \alpha_{ik} \right) P(c^i) = \sum_{i=1}^{K} \alpha_{Ki} P_0(c^i) + \gamma_K - \sum_{k=1}^{K} \lambda_k \gamma_k
$$

Implies

$$
\sum_{k=1}^{K} \lambda_k \alpha_{ik} = 0, i = 1, \dots, K - 1
$$
  

$$
\sum_{k=1}^{K} \lambda_k = 1
$$

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## Finding The Convex Combination

- **Each component decision rule of the mixture has an** expected gain that is a hyperplane in the axes *P*(*c*<sup>1</sup>)..., *P*(*c*<sup>*K*-1</sup>)
- The first *K* − 1 rows of the *i <sup>t</sup>h* column consists of the coefficients of  $P(c^1) \ldots, P(c^{K-1})$  for the *i<sup>th</sup>* hyperplane

$$
\begin{pmatrix}\n\alpha_{11} & \alpha_{21} & \dots & \alpha_{K1} \\
\alpha_{21} & \alpha_{22} & \dots & \alpha_{K2} \\
\vdots & & \vdots & \vdots \\
\alpha_{K-1,1} & \alpha_{K-1,2} & \dots & \alpha_{K-1,K} \\
1 & 1 & \dots & 1\n\end{pmatrix}\n\begin{pmatrix}\n\lambda_1 \\
\lambda_2 \\
\vdots \\
\lambda_{K-1} \\
\lambda_K\n\end{pmatrix} = \begin{pmatrix}\n0 \\
0 \\
\vdots \\
0 \\
1\n\end{pmatrix}
$$

### Dependence on Class Prior Probabilities



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## Conditional Expected Gains: All Decision Rules



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4 重 8 1 重 The game is played for a large number of trials.

- Nature chooses class *c* in accordance with class priors  $P(c^1) \ldots, P(c^K)$
- A measurement *d* is sampled in accordance with *P*(*d* | *c*)
- Bayes chooses decision rule to maximize expected gain under given class priors

Suppose nature chooses class priors so that the Bayes gain is minimized. Bayes chooses to maximize expected gain under worst priors. But suppose nature does not choose *c* in accordance with worst priors.

There is a mixed decision rule that guarantees that regardless of what class priors nature chooses, the expected gain is equal to the Bayes gain under the worst class priors. This is the maximin decision rule.

## Dependence on Class Prior Probabilities



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### **Definition**

A decision rule *f* is a Maximin Decision Rule if and only if

$$
\min_{P(c^1),...,P(c^K)} \sum_{j=1}^K E[e \mid c^j;f] P(c^j) \ge \min_{P(c^1),...,P(c^K)} \sum_{j=1}^K E[e \mid c^j;g] P(c^j)
$$

for any decision rule *g* where

$$
E[e \mid c^j; f] = \sum_{d \in D} \sum_{k=1}^K e(c^j, c^k) P(d \mid c^j) f_d(c^k)
$$

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### Determining the Maximin Decision Rule

$$
E[e; f] = E[e|c^1; f]P(c^1) + E[e|c^2; f]P(c^2)
$$
  
= 
$$
E[e|c^1; f]P(c^1) + E[e|c^2; f](1 - P(c^1))
$$
  
= 
$$
(E[e|c^1; f] - E[e|c^2; f])P(c^1) + E[e|c^2; f]
$$

Since a maximin decision rule has no dependence on the prior probability, we must have

$$
E[e|c^{1};f] - E[e|c^{2};f] = 0
$$
  

$$
E[e|c^{1};f] = E[e|c^{2};f]
$$

In this case,

$$
E[e; f] = E[e|c^1; f]
$$
  
= 
$$
E[e|c^2; f]
$$

### Theorem

*A decision rule f is a maximin decision rule if and only if*

$$
\min_{j=1,...,K} E[e \mid c^j; f] \geq \min_{j=1,...,K} E[e \mid c^j, g]
$$

*for any decision rule g.*

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#### Theorem

*A decision rule f is a maximin decision rule if and only if*

$$
\min_{P(c^1),...,P(c^K)} E[e; f, P(c^1),..., P(c^K)] \geq \min_{P(c^1),...,P(c^K)} E[e; g, P(c^1),..., P(c^K)]
$$

*for any decision rule g.*

#### Proof.

*Recall*

$$
E[e; f, P(c1),..., P(cK)] = E[e; f] = \sum_{j=1}^{K} E[e | cj; f] P(cj)
$$

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A decision rule *f* is a maximin decision rule if and only if the expected gain of *f* is the same as the expected gain of the Bayes rule under the worst possible prior class probabilities.

#### Theorem

*Let G be the Bayes Economic Gain under the worst prior class probabilities. Then f is a maximin decision rule if and only if*

$$
E[e \mid c^j; f] = G, j = 1, \ldots, K
$$

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Let  $P(c^1), \ldots, P(c^K)$  be given class prior probabilities. Let *f <sup>m</sup>*, *m* = 1, . . . , *M* be *M* deterministic decision rules satisfying

$$
G = \sum_{j=1}^{K} E[e \mid c^j; f^m] P(c^j), m = 1, ..., M
$$

Then there exists  $\lambda_m, \ \lambda_m \geq 0, \ m = 1, \ldots, M$ , and  $\sum_{m=1}^{M}$  $\sum_{m=1}^{m} \lambda_m = 1$  satisfying

$$
G = E[e \mid c^j; \sum_{m=1}^M \lambda_m f^m], j = 1, \ldots, K
$$

Note:

$$
E[e \mid c^j; \sum_{m=1}^M \lambda_m f^m] = \sum_{m=1}^M \lambda_m E[e \mid c^j; f^m]
$$

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Let  $P(c^1), \ldots, P(c^K)$  be the worst priors

- Let  $G_w$  be the worst Bayes gain
- Let *f <sup>m</sup>* be deterministic decision rules, *m* = 1, . . . , *M*

$$
\bullet \ \ G_w = \sum_{j=1}^K E[e \mid c^j; f^m] P(c^j)
$$

**•** Find convex combination  $\lambda_1, \ldots, \lambda_M$ 

$$
\bullet \ \ G_w = E[e \mid c^k; \sum_{m=1}^M \lambda_m f^m] = \sum_{m=1}^M \lambda_m E[e \mid c^j; f^m], \ j = 1, \ldots, K
$$

$$
\bullet\ \mathsf{Let}\ a_{jm}=E[e\mid c^j;f^m]
$$

• Find convex combination  $\lambda_1, \ldots, \lambda_M$  satisfying

$$
\bullet \ \ G_w = \sum_{m=1}^M \lambda_m a_{jm}, \ j = 1, \ldots, K
$$

### Existence of Mixed Decision Rule Strategy

#### Theorem

Let  $a_{im}$  be a real numbers,  $j = 1, \ldots, K$ ;  $m = 1, \ldots, M$ . Let  $\rho_j \geq 0$  and  $\sum_{j=1}^K \rho_j = 1$  . Suppose

$$
G=\sum_{j=1}^K p_j a_{jm}, m=1,\ldots,M
$$

*Then there exists*  $\lambda_m$ ,  $m = 1, \ldots, M$ ,  $\lambda_m \geq 0$  *and*  $\sum_{m=1}^{M} \lambda_m = 1$ *satisfying*

$$
G=\sum_{m=1}^M a_{jm}\lambda_m, \ j=1,\ldots,K
$$

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### Dependence on Class Prior Probabilities



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